partools: a Sensible Package for Large Data Sets

Norm Matloff University of California, Davis

November 4, 2024

The **partools** package is a general framework for parallel processing of large data sets and/or highly-computational algorithms. It can be viewed on two levels:

- A set of various utilities to increase the usefulness of the R built-in package 'parallel'.
- An "un-MapReduce" paradigm, avoiding the drawbaccks while retaining the philosophy of highly-distributed memory objects and files of Hadoop and Spark.

1 Motivation

With the advent of Big Data, the Hadoop framework became ubiquitous in the years following its birth in 2006. Yet it was clear from the start that Hadoop had major shortcomings in performance, and eventually these came under serious discussion¹ This resulted in a new platform, Spark, gaining popularity. As with Hadoop, there is an R interface available for Spark, named SparkR.

Spark overcomes one of Hadoop's major problems, which is the lack of ability to cache data in a multi-pass computation. However, Spark unfortunately retains the drawbacks of Hadoop:

- Spark still relies on a MapReduce paradigm, featuring a shuffle (systemwide sort) operation after each pass of the data. This can be quite slow.²
- Thus SparkR can be considerably slower than Plain Old R (POR).
- Hadoop/Spark have a complex, rather opaque infrastructure, and rely on Java/Scala. This makes them difficult to install, configure and use for those who are not computer systems experts.
- Although a major plus for Hadoop/Spark is fault tolerance, it is needed only for users working on extremely large clusters, consisting of hundreds or thousands of nodes. Disk failure rates are simply too low for fault tolerance to be an issue for many users who think they need Hadoop/Spark but who do not have such large systems.³

 $^{^1 {\}rm See}$ for example "The Hadoop Honeymoon is Over," https://www.linkedin.com/pulse/hadoop-honeymoon-over-martyn-jones

²See "Low-Rank Matrix Factorizations at Scale: Spark for Scientific Data Analytics," Alex Gittens, MMDS 2016 in the C context, and "Size of Datasets for Analytics and Implications for R," Szilard Pafka, useR! 2016, in the R context.

 $^{^{3}}$ https://wiki.apache.org/hadoop/PoweredBy

The one firm advantage of Hadoop/Spark is their use of distributed file systems. Under the philosophy, "Move the computation to the data, rather than *vice versa*," network traffic may be greatly reduced, thus speeding up computation.

In addition, this approach helps deal with the fact that Big Data sets may not fit into the memory of a single machine. (This aspect is too often overlooked in discussions of parallel/distributed systems.)

1.1 An Alternative to Hadoop/Spark

Therefore:

It is desirable to have a package that retains the distributed-file nature of Hadoop/Spark while staying fully within the simple, familiar, yet powerful POR framework, no Java or other external language needed.

The **partools** package is designed to meet these goals. It is intended as **a simple**, **sensible POR alternative to Hadoop/Spark**. Though not necessarily appropriate for all settings, for many R programmers, **partools** may be a much better choice than **Hadoop/Spark**.

The package does not provide fault tolerance of its own. If this is an issue, one can provide it externally, say with the XtreemFS system.

1.2 Software Alchemy

Some of the package's functions perform an operation I call Software Alchemy (SA).

Consider a large linear regression application. We might consider dividing the data into chunks, calling lm() on each chunk, then simply average the estimated coefficient vector over chunks. It can be shown that under fairly general conditions, this works, in the sense of producing estimators with the same asymptotic variance as that of the original estimator.

This technique was developed independently by a number of researchers. I call it Software Alchemy, as it turns non-embarassingly parallel problems into embarassingly parallel ones.⁴

2 Where Is the Magic?

As you will see later, **partools** can deliver some impressive speedups. But there is nothing magical about this. Instead, the value of the package stems from just two simple sources:

- (a) The package follows a Keep It Distributed philosophy: Form distributed objects and keep using them in distributed form throughout one's R session, avoiding wherever possible time-consuming transfer of data between the workers and the manager.
- (b) The package consists of a number of utility functions that greatly facilitate creating and storing and distributed objects, both in memory and on disk, and distributed applications such as for regression and classification.

⁴Software Alchemy: Turning Complex Statistical Computations into Embarrassingly-Parallel Ones, Norman Matloff, Journal of Statistical Software, 71 (2016).

3 Overview of the partools Package

The package is based on the following very simple principles, involving *distributed files* and *distributed data frames/matrices*. We'll refer to nondistributed files and data frames/matrices as *monolithic*.

- Files are stored in a distributed manner, in files with a common basename. For example, the virtual file \mathbf{x} is stored as separate files $\mathbf{x.01}$, $\mathbf{x.02}$ etc.
- Data frames and matrices are stored in memory at the nodes in a distributed manner, with a common name. For example, the data frame **y** is stored in chunks at the cluster nodes, each chunk known as **y** at its node.

3.1 Platforms

Through the use of virtual clusters in the R 'parallel' package, these tools can be used either on multicore machines or physical clusters, such as in the cloud. With the latter, a very high degree of parallelism is potentially possible.

We will speak of a 'parallel' cluster has having a *manager*, sends work to and receives work from the *worker nodes*.

3.2 Package Structure

Again, in a distributed file, all the file chunks have the same prefix, and in a distributed data frame, all chunks have the same name at the various cluster nodes. This plays a key role in the software.

The package consists of three main groups of functions:

3.2.1 Distributed-file and distributed-data frame functions

- filesplit(): Create a distributed file from monolithic one.
- filesplitrand(): Create a distributed file from monolithic one, but randomize the record order.
- filecat(): Create a monotlithic file from distributed one.
- fileread(): Read a distributed file into distributed data frame.
- **readnscramble():** Read a distributed file into distributed data frame, but randomize the record order.
- filesave(): Write a distributed data frame to a distributed file.
- filechunkname(): Returns the full name of the file chunk, associated with the calling cluster node, including suffix, e.g. '01', '02' etc.
- distribult(): Create a distributed data frame/matrix from monotlithic one.
- distribcat(): Create a monotlithic data frame/matrix from distributed one.

3.2.2 Tabulative functions

- distribagg(): Distributed form of R's aggregate().
- distribcounts(): Wrapper for distribagg() to obtain table cell counts.
- dfileagg(): Like distribagg(), but file-based rather than in-memory, in order to handle files that are too big to fit in memory, even on a distributed basis.
- distribgetrows(): Applies an R subset() or similar filtering operation to the distributed object, and collects the resulting rows into a single object at the caller.
- distribrange(): Distributed form of R's range().

3.3 Classical Computational Functions

- ca(): General SA algorithm.
- cabase(): Core of ca().
- **caagg():** SA analog of **distribagg()**.
- **cameans()**: Finds means in the specified columns.
- caquantile(): Wrapper for SA version of R's quantile().
- calm(): Wrapper for SA version of R's lm().
- caglm(): Wrapper for SA version of R's glm().
- cakm(): Wrapper for SA version of R's kmeans().
- caprcomp(): Wrapper for SA version of R's prcomp().

3.4 Modern Statistical/Machine Learning Functions

- caclassfit(): Wrapper to do distributed fitting of a multiclass classification method such as random forests (**rpart** package) or SVM (e1071 package).
- caclasspred Does prediction on new data from the output of caclassfit().

3.5 Support Functions

- formrowchunks(): Form chunks of rows of a data frame/matrix.
- matrixtolist(): Forms an R list of the rows or columns of a data frame or matrix, one row/column per list element.
- addlists(): "Add" two R lists, forming a new one. If an element name appears in the two input lists, that name will appear in the new one, with value equal to the "sum" of the two input values, calculated by sum(), cat() or other user-specified function.
- dbs(), dbsmsg(), etc.: Debugging aids.

3.6 More on Software Alchemy

All the functions with names beginning with "ca" use the Software Alchemy (SA) method. The idea is simple: Apply the given estimator to each chunk in the distributed object, and average over chunks. It is proven that the resulting distributed estimator has the same statistical accuracy — the same asymptotic variance — as the original serial one.⁵

A variant, suitable in many regression and classification algorithms, retains the chunk output in the result, rather than performing an avereging process. Consider for instance the use of LASSO for regression.⁶ Each chunk may settle on a different subset of the predictor variables, so it would not make sense to average the estimated coefficient vectors. Instead, the predictor subsets and corresponding coefficients are retained in the SA output. When one is faced with predicting the response variable for a new data point, a prediction is calculated from each chunk, and those predictions are averaged to obtain the final prediction for the new point. In a classification context, voting may be used.

Note that SA requires that the data be i.i.d. If the data was stored in some sorted order — in the flight data below, it was sorted by date — it needs to be randomize it first, using one of the functions provided by **partools** for this purpose.

4 Sample Session

Our data set, from *http://stat-computing.org/dataexpo/2009/the-data.html* consists of the wellknown records of airline flight delay. For convenience, we'll just use the data for 2008, which consists of about 7 million records. This is large enough to illustrate speedup due to parallelism, but small enough that we won't have to wait really long amounts of time in our sample session here.

The session was run on a 16-core machine, with a 16-node R virtual cluster in the sense of the R **parallel** package (which is loaded by **partools**). Note carefully, though, that we should not expect a 16-fold speedup. In the world of parallel computation, one usually gets of speedups of considerably less than n for a platform of n computational entities, in this case with n = 16. Indeed, one is often saddened to find that the parallel version is actually *slower* than the serial one!

To create our cluster **cls**, we ran

```
> cls <- makeCluster(16) # from 'parallel' library
> setclsinfo(cls) # 'partools' initialization function
```

4.1 Distribute the Data

The file, **2008.csv**, was first split into a distributed file, stored in **yr2008r.01**,...,**yr2008r.16**, using **filesplitrand()**, and then read into memory at the 16 cluster nodes using **fileread()**:

```
> filesplitrand(cls,'2008.csv','yr2008r',2,header=TRUE,sep=",")
```

```
> fileread(cls,'yr2008r','yr2008',2,header=TRUE, sep=",")
```

⁵In the world of parallel computation, the standard word for nonparallel is *serial*.

⁶Not currently available in the package, but easily coded under its framework.

The call to **filesplitrand()** splits the file as described above; since these files are permanent, we can skip this step in future R sessions involving this data (if the data doesn't change). The function **filesplitrand()** was used instead of **filesplit()** to construct the distributed file, in order to randomize the placement of the records of **yr2008** across cluster nodes. As noted earlier, random arrangement of the rows is required for SA.

The argument 2 here means that the suffixes are 2 digits, specifically '01', '02' and so on. So, we create files **yr2008r.01** etc. using **filesplit()**. The call to **fileread()** specifies that cluster node 1 will read the file **yr2008r.01**, cluster node 2 will read **yr2008r.02** and so on. Each node will place the data it reads into a local data frame **yr2008**.

Our data is now distributed across the memories of cluster nodes. Of course, if we did not need permanent distributed file storage, we could have just read in the original file into a large data frame at the manager node, then distributed the data frame to the nodes via **distribusplit()**.

4.2 Distributed Aggregation of Summary Statistics

In order to run timing comparisons, the full file was also read into memory at the cluster manager:

> yr2008 <- read.csv("yr2008")

(In practice, though, this would not be done, i.e. we would not have *both* distributed *and* monotlithic versions of the data at the same time.)

The first operation run involved the package's distributed version of R's **aggregate()**. Here we wanted to tabulate departure delay, arrival delay and flight time, broken down into cells according to flight origin and destination. We'll find the maximum value in each cell.

```
> system.time(print(distribagg(cls, c("DepDelay","ArrDelay","AirTime"),
   c("Origin", "Dest"), "yr2008", FUN="max")))
. . .
        CDV
             YAK
                        327
                                  325
                                            54
5193
5194
        JNU
              YAK
                        317
                                  308
                                           77
5195
        SLC
              YKM
                        110
                                  118
                                           115
        IPL
              YUM
                                            26
5196
                        162
                                  163
. . .
   user system elapsed
  2.291
          0.084 15.952
```

What **distribagg()** did here was have each cluster node run **aggregate()** on its own chunk of the data, then (pardon the pun) aggregate the return values from the nodes.

The serial version was much slower.

```
> system.time(print(aggregate(cbind(DepDelay,ArrDelay,AirTime) ~
   Origin+Dest,data=yr2008,FUN=max)))
. . .
5193
        CDV
             YAK
                       327
                                 325
                                           54
5194
        JNU
             YAK
                       317
                                 308
                                           77
        SLC
              YKM
5195
                       110
                                 118
                                          115
```

5196 IPL YUM 162 163 26 ... user system elapsed 249.038 0.444 249.634

So, the results of **distribagg()** did indeed match those of **aggregate()**, but did so more than 15 times faster!

4.3 Un-distributing Data

Remember, the Keep It Distributed philosophy of **partools** is to create distributed objects and then keep using them repeatedly in distributed form. However, in some cases, we may wish to collect a distributed result into a monolithic object. This is done in the next example:

Say we wish to do a filter operation, extracting the data on all the Sunday evening flights, and collect it into one place. Here is the direct version:

> sundayeve <- with(yr2008,yr2008[DayOfWeek==1 & DepTime > 1800,])

This actually is not a time-consuming operation, but again, in typical **partools** use, we would only have the distributed version of **yr2008**. Here is how we would achieve the same effect from the distributed object:

```
> sundayeved <-
    distribgetrows(cls,'with(yr2008,yr2008[DayOfWeek==1 & DepTime > 1800,])')
```

What **distribgetrows()** does is produce a data frame at each cluster node, per the user's instructions, then combine them together at the caller via R's **rbind()**. The user sets the second argument, a quoted string, to whatever she would have done on a serial basis. A simple concept, yet quite versatile.

4.4 Integration with parallel

partools uses the **parallel** package, so one can leverage the functions in **parallel** to compute on objects created through **partools**. **clusterEvalQ()** evaluates expressions on each of the workers, and is useful for interacting with existing distributed objects. Below are a few examples.

object.size() estimates the size of the objects in memory.

```
> clusterEvalQ(cls, {
+     object.size(yr2008)
+ })
[[1]]
406905480 bytes
[[2]]
406905592 bytes
```

This code ran on a two node local cluster. Each of the two distributed objects occupies around 400 MB.

We can create a new column in **yr2008** by calculating the minute of arrival or departure. One way to do this is to write and test a function locally, use **clusterExport()** to send it to the cluster, and finally evaluate it with **clusterEvalQ()**.

```
minute <- function(x){</pre>
    x <- as.character(x)</pre>
    # Necessary to preserve NA values
    x[is.na(x)] <- ""
    matches <- regexpr(".?.?$", x)</pre>
    two_right_digits <- regmatches(x, matches)</pre>
    as.integer(two_right_digits)
}
# Verify locally that code behaves as expected
minute(c(NA, 1L, 20L, 329L, 1900L))
# [1] NA 1 20 29 0
# Send the function to the data
clusterExport(cls, "minute")
# Evaluate this expression on each worker node
clusterEvalQ(cls, {
    yr2008$ArrMinute <- minute(yr2008$ArrTime)</pre>
    yr2008$DepMinute <- minute(yr2008$DepTime)</pre>
    NULL # Keeps It Distributed
})
```

The **NULL** at the end of the **clusterEvalQ** here is quite important, since otherwise data will be unnecessarily transferred to the manager. An alternative to the above approach is to write a function to do global assignment within the workers using **«-** , but this is more difficult to verify correct behavior.

4.5 Distributed NA Processing

As another example, say we are investigating data completeness. We may wish to flag all records having an inordinate number of NA values. As a first step, we may wish to add a column to our data frame, indicating how many NA values there are in each row. If we did not have the advantage of distributed computation, here is how long it would take for our flight delay data:

```
> sumna <- function(x) sum(is.na(x))
> system.time(yr2008$n1 <- apply(yr2008[,c(5,7,8,11:16,19:21)],1,sumna))
    user system elapsed
268.463 0.773 269.542</pre>
```

But it is of course much faster on a distributed basis:

```
> clusterExport(cls,"sumna",envir=environment())
> system.time(clusterEvalQ(cls,yr2008$n1 <- apply(yr2008[,c(5,7,8,11:16,19:21)],1,sumna)))
    user system elapsed
    0.094    0.012    16.758</pre>
```

The speedup here was about 16, fully utilizing all 16 cores.

Ordinarily, we would continue that NA analysis on a distributed basis, in accord with the **partools** Keep It Distributed philosophy of setting up distributed objects and then repeatedly dealing with them on a distributed basis. If our subsequent operations continue to have time complexity linear in the number of records processes, we should continue to get speedups of about 16.

On the other hand, we may wish to gather together all the records have 8 or more NA values. In the nonparallel context, it would take some time:

```
> system.time(na8 <- yr2008[yr2008$n1 > 7,])
    user system elapsed
    9.292    0.028    9.327
```

In the distributed manner, it is slightly faster:

```
> system.time(na8d <- distribgetrows(cls,'yr2008[yr2008$n1 > 7,]'))
user system elapsed
5.524 0.160 6.584
```

The speedup is less here, as the resulting data must travel from the cluster nodes to the cluster manager. In our case here, this is just a memory-to-memory transfer rather than across a network, as we are on a multicore machine, but it still takes time. If the number of records satisfying the filtering condition had been smaller than the 136246 we had here, the speedup factor would have been greater.

5 SA: Software Alchemy

Now let's turn to statistical operations, starting of course with linear regression. As noted, some **par-tools** functions make use of Software Alchemy, which replaces the given operation by a *distributed*, *statistically equivalent* operation. This will often produce a significant speedup. Note again that though the result may different from the non-distributed version, say in the third significant digit, it is just as accurate statistically; neither estimate is "better" than the other.

The SA function names begin with 'ca', for "chunk averaging." The SA version of lm(), for instance, is calm().

5.1 SA: Linear Regression

In the flight data, we predicted the arrival delay from the departure delay and distance, comparing the distributed and serial versions,

```
> system.time(print(lm(ArrDelay ~ DepDelay+Distance,data=yr2008)))
```

```
Coefficients:
(Intercept)
                DepDelay
                             Distance
  -1.061369
                1.019154
                            -0.001213
  user system elapsed
77.107 12.463 76.225
> system.time(print(calm(cls, 'ArrDelay ~ DepDelay+Distance,data=yr2008')$tht))
 (Intercept)
                 DepDelay
                              Distance
-1.061262941 1.019150592 -0.001213252
  user system elapsed
         0.691 18.396
13.414
```

Note again the quoted-string argument. This is the one the user will give to lm() in the serial case.

Linear regression is very hard to parallelize, so the speedup factor of more than 4 here is nice. Coefficient estimates were virtually identical.

5.2 SA: Principal ComponentsRegression

Next, principal components. Since R's **prcomp()** does not handle NA values for nonformula specifications, let's do that separately first:

```
> system.time(cc <- na.omit(yr2008[,c(12:16,19:21)]))
    user system elapsed
    9.540    0.351    9.907
> system.time(clusterEvalQ(cls,cc <- na.omit(yr2008[,c(12:16,19:21)])))
    user system elapsed
    0.885    0.232    2.352</pre>
```

Note that this too was faster in the distributed approach, though both times were small. And now the PCA runs:

```
> system.time(ccout <- prcomp(cc))
    user system elapsed
61.905 49.605 58.444
> ccout$sdev
[1] 5.752546e+02 5.155227e+01 2.383117e+01 1.279210e+01 9.492825e+00
[6] 5.530152e+00 1.133015e-03 6.626621e-12
> system.time(ccoutdistr <- caprcomp(cls,'cc',8))
    user system elapsed
    5.023 0.604 8.949
> ccoutdistr$sdev
[1] 5.752554e+02 5.155127e+01 2.383122e+01 1.279184e+01 9.492570e+00
[6] 5.529869e+00 9.933142e-04 8.679427e-13
```

Once again, the second argument of **caprcomp()** is a quoted string, in which the user specifies the desired arguments to **prcomp()**. Since those arguments may be complicated, the code cannot deduce the number of variables, and thus needs to be specified in the third argument.

We have more than a 6-fold speedup here. Agreement of the component standard deviations is good.⁷

5.3 SA: K-Means Clustering

The package also includes a distributed version of k-means clustering. Here it is run on the flight delay data. First, retain only the NA-free rows for the variables of interest, then run:

```
> fileread(cls,'yr2008r','yr2008',2,header=TRUE, sep=",")
> invisible(clusterEvalQ(cls,y28 <- na.omit(yr2008[,c(5:8,13:16,19:21)])))
> system.time(koutpar <- cakm(cls,'y28',3,11))
    user system elapsed
    4.083    0.132    9.293</pre>
```

Compare to serial:

```
> yr2008 <- read.csv('y2008')
> y28 <- na.omit(yr2008[,c(5:8,13:16,19:21)])
> system.time(koutser <- kmeans(y28,3))
    user system elapsed
54.394 0.558 55.032</pre>
```

So, the distributed version is about 6 times faster. Results are virtually identical:

```
> koutpar$centers
          [,1]
                    [,2]
                             [,3]
                                      [,4]
                                                [,5]
[1,] 1741.3967 1718.0296 1876.433 1895.435 110.4398
[2,] 932.4057 936.6907 1081.743 1082.813 108.5091
[3,] 1311.2193 1308.1838 1496.267 1525.790 267.8620
          [,6]
                    [,7]
                              [,8]
                                        [,9]
                                                [,10]
[1,] 85.25672 13.101844 14.826940 569.2534 6.742315
[2,] 84.66763 3.091913 4.517502 561.0567 6.785464
[3,] 238.93152 8.668587 11.698193 1886.8964 7.541735
        [, 11]
[1,] 16.71571
[2,] 15.63046
[3,] 18.35916
> koutser$centers
    DepTime CRSDepTime ArrTime CRSArrTime
1 1741.3888
            1718.0217 1876.418
                                  1895.425
2 932.3681
              936.6674 1081.737
                                  1082.809
3 1311.4436 1308.3525 1496.404
                                  1525.905
  CRSElapsedTime
                   AirTime ArrDelay DepDelay
        110.4363 85.25292 13.100842 14.826083
1
2
        108.5151 84.67361 3.092439 4.518112
```

⁷Note that the last component, i.e. the eighth one, is minuscule, statistically 0. Again, SA gives results that are statistically equivalent to the serial ones.

```
3 267.8669 238.93668 8.672439 11.701706
Distance TaxiIn TaxiOut
1 569.2226 6.742079 16.71604
2 561.1148 6.785409 15.63038
3 1886.9094 7.542760 18.35823
```

5.4 SA: Multiclass Classification

Here we apply random forests to the UC Irvine forest cover type data, which has 590,000 records of 55 variables. The last variable is the cover type, coded 1 through 7. The machine used was quad core with hyperthreading level of 2, giving a theoretically possible parallelism degree of 8. Thus a cluster of size 8 was tried.

We used random forests for our classification algorithm (perhaps appropriate, given the data here!), but could have used any algorithm whose R implemention has a **predict()** method. (Some output not shown.)

```
> library(rpart)
> cls <- makeCluster(8)</pre>
> setclsinfo(cls)
> clusterEvalQ(cls,library(rpart)) # have each node load pkg
> cvr <- read.csv('~/Research/DataSets/ForestCover/CovTypeFull.csv',</pre>
     header=FALSE)
> cvr$V55 <- as.factor(cvr$V55) # rpart requires factor for class</pre>
> trnidxs <- sample(1:580000,290000) # form training and test sets
> trn <- cvr[trnidxs.]</pre>
> tst <- cvr[-trnidxs,]</pre>
> distribsplit(cls,'trn')
# do fit at each node; again, one argument is the serial argument
> system.time(fit <- caclassfit(cls,'rpart(V55 ~ .,data=trn,xval=25)'))</pre>
   user system elapsed
 0.126
          0.005 25.294
> system.time(predout <- caclasspred(fit,tst,55,type='class'))</pre>
   user system elapsed
 26.132
          0.910 27.045
> predout$acc
[1] 0.6692542
> system.time(fitser <- rpart(V55 ~ .,data=trn,xval=25))</pre>
   user system elapsed
87.699
          0.143 87.850
> # system.time(predoutser <- predict(fitser,tst[,-10],type='class'))</pre>
> system.time(predoutser <- predict(fitser,tst[,-55],type='class'))</pre>
   user system elapsed
 0.302
          0.101
                   0.403
> mean(predoutser == tst[,55])
[1] 0.6691202
```

What **caclassfit()** does is run our classification algorithm, in this case **rpart**, at each node, then collect all the fitted models and return them to the caller. So here, after the call, **fit** will be an R

list, element i of which is the fit computed by cluster node i.

The call to **caclasspred()** then applies these fits (on the parent node, not the cluster nodes) to our test data, **tst**. The result, **predout** contains the predictions for each of the 149 cases in **tst**, using voting among the eight fits.

Here SA more than tripled the fitting speed, with the same accuracy. Prediction using SA is relatively slow, due to the voting process, but arguably this is not an issue in a production setting, and in any case, SA was substantially faster even in total fitting plus prediction time.

6 Dealing with Memory Limitations

The discussion so far has had two implicit assumptions:

- The number of file chunks and the number of (R **parallel**) cluster nodes are equal, and the latter is equal to the number of physical computing devices one has, e.g. the number of cores in a multicore machine or the number of network nodes in a physical cluster.
- Each file chunk fits into the memory⁸ of the corresponding cluster node.

The first assumption is not very important. If for some reason we have created a distributed file with more chunks than our number of physical computing devices, we can still set up an R **parallel** cluster with size equal to the number of file chunks. Then more than one R process will run on at least some of the cluster nodes, albeit possibly at the expense of, say, an increase in virtual memory swap operations.

The second assumption is the more pressing one. For this reason, the **partools** package includes functions such as **dfileagg()**. The latter acts similarly to **distribagg()**, but with a key difference: Any given cluster node will read from many chunks of the distributed file, and will process those chunks one at a time, never exceeding memory constraints.

Consider again our flight delay data set. As a very simple example, say we have a two-node physical cluster, and that each node has memory enough for only 1/4 of the data. So, we break up the original data file to 4 pieces, **yr2008.1** through **yr2008.4**, and we run, say,

Our first cluster node will read **yr2008.1** and **yr2008.2**, one at a time, while the second will read **yr2008.3** and **yr2008.4**, again one at a time, At each node, at any given time only 1/4 of the data is in memory, so we don't exceed memory capacity. But they will get us the right answer, and will do so in parallel, roughly with a speedup factor of 2.

More functions like this will be added to **partools**.

⁸Say, physical memory plus swap space.